

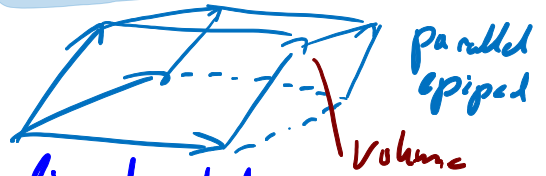
- Recap:
- vector space \mathbb{R}^n , matrices, basis, dimension
 - linear maps, Gaussian elimination

4

Determinants

Let $A \in \mathbb{R}^{n \times n}$ be a square matrix. The determinant $\det(A) \in \mathbb{R}$ of A is a special real number, associated to A .

- measures "volumes"



- $\det(A) = 0 \Leftrightarrow$ columns are lin. dependent
 $\Leftrightarrow A$ is not invertible

- sign \rightsquigarrow orientation, $\det(\mathbb{1}) = 1$



- Properties of a volume?

4.1 Determinant in two dimensions

We already know how to solve the system $Ax = b$ if A is a square matrix. The determinant should then tell us if the system has a unique solution before solving it. For a 2×2 LES, we get (for $a_{11} \neq 0$):

$$\begin{array}{l} E_1 \rightarrow \\ E_2 \rightarrow \end{array} \left(\begin{array}{cc|c} a_{11} & a_{12} & b_1 \\ a_{21} & a_{22} & b_2 \end{array} \right) \quad \begin{array}{l} E_2 - \frac{a_{21}}{a_{11}} E_1 \\ \sim a_{11} \cdot E_2 \end{array} \left(\begin{array}{cc|c} a_{11} & a_{12} & b_1 \\ 0 & a_{11}a_{22} - a_{12}a_{21} & b_2a_{11} - b_1a_{21} \end{array} \right)$$

$\neq 0 \Leftrightarrow$ unique solution
 (2 points, $\text{Ker}(A) = \{0\}$,
 $\text{Ran}(A) = \mathbb{R}^2$)

Definition 4.1.

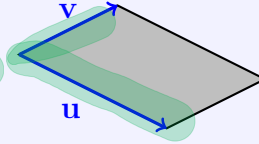
For a matrix $A = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \in \mathbb{R}^{2 \times 2}$, we call $\det(A) := a_{11}a_{22} - a_{12}a_{21}$ the determinant of A .

The determinant in two dimensions has an immediate interpretation when we compare it

to an area measurement:

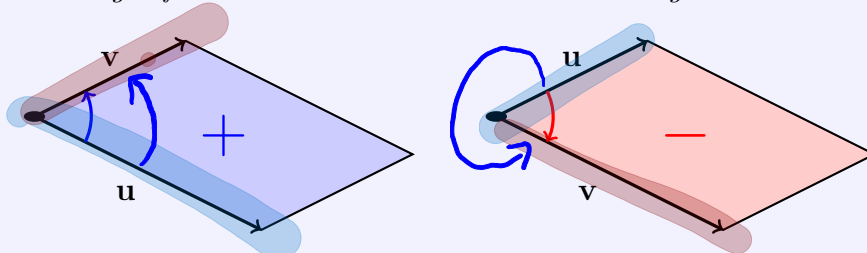
Consider two vectors $\mathbf{u} = \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}$ and $\mathbf{v} = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}$ from \mathbb{R}^2 and the spanned parallelogram. We define $\text{Area}(\mathbf{u}, \mathbf{v}) \in \mathbb{R}$ as the real number that fulfils

$$|\text{Area}(\mathbf{u}, \mathbf{v})| = \text{area of parallelogram}$$

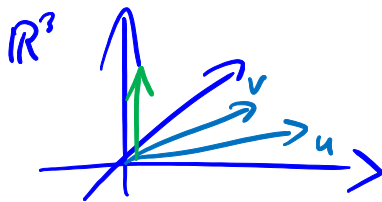


and the sign of $\text{Area}(\mathbf{u}, \mathbf{v})$ is chosen in the following way:

- **Plus sign** if then rotation by rotating \mathbf{u} such that the angle between \mathbf{u} and \mathbf{v} gets smaller is the mathematical positive sense,
- **Minus sign** if this rotation is the mathematical negative sense.



Recall Section 2.6: Area of parallelogram \Leftrightarrow cross product (in \mathbb{R}^3)



x - y -plane $\Leftrightarrow \mathbb{R}^2$

$$\tilde{\mathbf{u}} := \begin{pmatrix} u_1 \\ u_2 \\ 0 \end{pmatrix} \quad \text{and} \quad \tilde{\mathbf{v}} := \begin{pmatrix} v_1 \\ v_2 \\ 0 \end{pmatrix}$$

$$\Rightarrow \tilde{\mathbf{u}} \times \tilde{\mathbf{v}} = \begin{pmatrix} u_1 \\ u_2 \\ 0 \end{pmatrix} \times \begin{pmatrix} v_1 \\ v_2 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ u_1 v_2 - u_2 v_1 \end{pmatrix}$$

Then we find:

$$|\text{Area}(\mathbf{u}, \mathbf{v})| = \|\tilde{\mathbf{u}} \times \tilde{\mathbf{v}}\| = \left\| \begin{pmatrix} u_2 \cdot 0 - 0 \cdot v_2 \\ 0 \cdot v_1 - u_1 \cdot 0 \\ u_1 v_2 - u_2 v_1 \end{pmatrix} \right\| = \left\| \begin{pmatrix} 0 \\ 0 \\ u_1 v_2 - u_2 v_1 \end{pmatrix} \right\| = |u_1 v_2 - u_2 v_1|$$

Without the absolute value this coincides with the determinant of the matrix

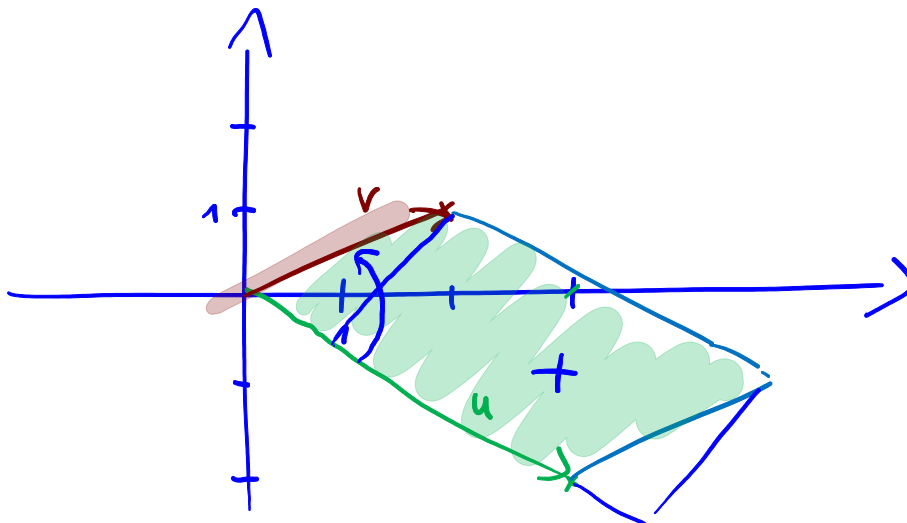
$$A := \begin{pmatrix} | & | \\ \mathbf{u} & \mathbf{v} \\ | & | \end{pmatrix} \in \mathbb{R}^{2 \times 2}$$

Indeed, also the sign rule from above is fulfilled. (right-hand rule)

Proposition 4.2.

$$\text{Area}\left(\begin{pmatrix} u_1 \\ u_2 \end{pmatrix}, \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}\right) = \det \begin{pmatrix} u_1 & v_1 \\ u_2 & v_2 \end{pmatrix} = u_1 v_2 - u_2 v_1 \quad (4.1)$$

Example 4.3. (a) If we look at $\mathbf{u} = \begin{pmatrix} 3 \\ -2 \end{pmatrix}$ and $\mathbf{v} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$, we get:



$$\text{Area}(\mathbf{u}, \mathbf{v}) = \text{Area}\left(\begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \end{pmatrix}\right) = 3 \cdot 1 - (-2) \cdot 2 = 7.$$

The area is 7 and the orientation is positive.

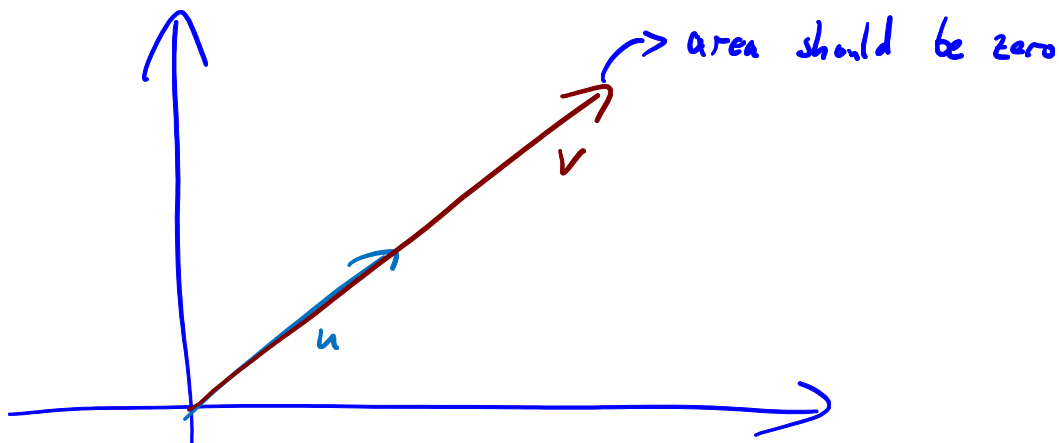
(b) The other ordering gets:

$$\text{Area}\left(\begin{pmatrix} 2 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}\right) = 2 \cdot (-2) - 1 \cdot 3 = -7.$$

The area is again 7 but the orientation is negative.

(c) Choose $\mathbf{u} = \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}$ and the scaled vector $\mathbf{v} = \alpha\mathbf{u} = \begin{pmatrix} \alpha u_1 \\ \alpha u_2 \end{pmatrix}$. Then:

$$\text{Area}(\mathbf{u}, \mathbf{v}) = \text{Area}(\mathbf{u}, \alpha\mathbf{u}) = \text{Area}\left(\begin{pmatrix} u_1 \\ u_2 \end{pmatrix}, \begin{pmatrix} \alpha u_1 \\ \alpha u_2 \end{pmatrix}\right) = u_1 \alpha u_2 - u_2 \alpha u_1 = 0.$$



in \mathbb{R}^2 : area

4.2 Determinant as a volume measure *in \mathbb{R}^3 "usual" volume*

\leadsto n-dim. volume

in \mathbb{R}^1 : length

\leadsto Volume function Vol_n ($\text{Vol}_2 = \text{Area}$)

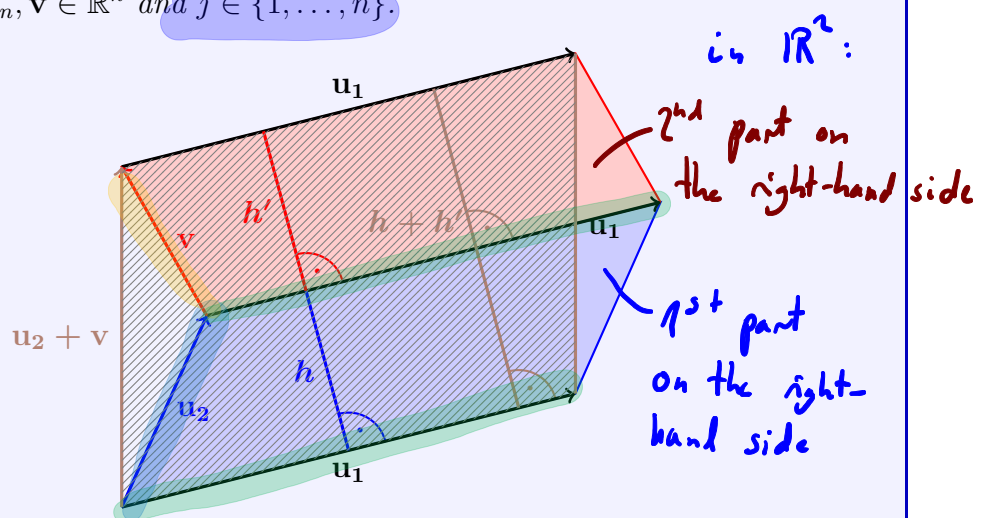
\hookrightarrow properties we expect of a volume function!

Definition 4.4. Properties that Vol_n should have.

The n -dimensional volume function $\text{Vol}_n : \mathbb{R}^n \times \dots \times \mathbb{R}^n \rightarrow \mathbb{R}$ that gets n vectors as input should fulfil:

(1) $\text{Vol}_n(\mathbf{u}_1, \dots, \mathbf{u}_j + \mathbf{v}, \dots, \mathbf{u}_n) = \text{Vol}_n(\mathbf{u}_1, \dots, \mathbf{u}_j, \dots, \mathbf{u}_n) + \text{Vol}_n(\mathbf{u}_1, \dots, \mathbf{v}, \dots, \mathbf{u}_n)$
 for all $\mathbf{u}_1, \dots, \mathbf{u}_n, \mathbf{v} \in \mathbb{R}^n$ and $j \in \{1, \dots, n\}$.

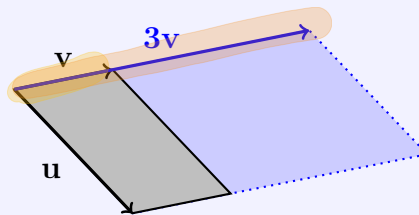
$\text{Vol}_2(\mathbf{u}_1, \mathbf{u}_2 + \mathbf{v}) = \text{Vol}_2(\mathbf{u}_1, \mathbf{u}_2) + \text{Vol}_2(\mathbf{u}_1, \mathbf{v})$



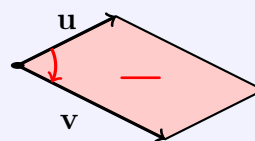
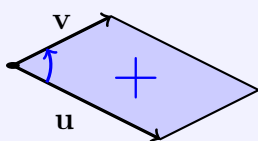
(Picture in the case $n = j = 2$)

(2) $\text{Vol}_n(\mathbf{u}_1, \dots, \alpha \mathbf{u}_j, \dots, \mathbf{u}_n) = \alpha \text{Vol}_n(\mathbf{u}_1, \dots, \mathbf{u}_j, \dots, \mathbf{u}_n)$ for all $\mathbf{u}_1, \dots, \mathbf{u}_n \in \mathbb{R}^n$, $\alpha \in \mathbb{R}$ and $j \in \{1, \dots, n\}$.

$\text{Vol}_2(\mathbf{u}_1, 3\mathbf{v}) = 3 \text{Vol}_2(\mathbf{u}_1, \mathbf{v})$



(3) $\text{Vol}_n(\mathbf{u}_1, \dots, \mathbf{u}_i, \dots, \mathbf{u}_j, \dots, \mathbf{u}_n) = -\text{Vol}_n(\mathbf{u}_1, \dots, \mathbf{u}_j, \dots, \mathbf{u}_i, \dots, \mathbf{u}_n)$ for all $\mathbf{u}_1, \dots, \mathbf{u}_n \in \mathbb{R}^n$, and $i, j \in \{1, \dots, n\}$ with $i \neq j$.



(4) The unit cube ($\mathbf{u}_1 = \mathbf{e}_1, \dots, \mathbf{u}_n = \mathbf{e}_n$) has volume 1: $\text{Vol}(\mathbf{e}_1, \dots, \mathbf{e}_n) = 1$.



Vol_n : (1), (2) linear in each component
 (3) antisymmetric
 (4) normalised

First, we show an easy consequence that follows from the two properties (2) and (3):

Proposition 4.5. Colinear vectors do not have an area.

For all $\mathbf{u} \in \mathbb{R}^2$ and $\alpha \in \mathbb{R}$, we have $\text{Vol}_2(\mathbf{u}, \alpha\mathbf{u}) = 0$.

$\rightarrow ? \text{Vol}_2(\mathbf{u}, \mathbf{u}) = 0$

Proof. Because of (3), we find $\text{Vol}_2(\mathbf{u}, \mathbf{u}) = -\text{Vol}_2(\mathbf{u}, \mathbf{u})$ and this implies $\text{Vol}_2(\mathbf{u}, \mathbf{u}) = 0$. Since (2) holds, we get $\text{Vol}_2(\mathbf{u}, \alpha\mathbf{u}) = \alpha \text{Vol}_2(\mathbf{u}, \mathbf{u}) = \alpha \cdot 0 = 0$. \square

Now, we can prove the formula (4.1):

Proposition 4.6.

If Vol_2 fulfils (1), (2), (3), (4), then for all $\mathbf{u} = \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}, \mathbf{v} = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \in \mathbb{R}^2$ the following

holds $\text{Vol}_2(\mathbf{u}, \mathbf{v}) = \text{Vol}_2\left(\begin{pmatrix} u_1 \\ u_2 \end{pmatrix}, \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}\right) = \underline{+u_1v_2 - u_2v_1}$.

$$\begin{array}{cc} \underline{u_1} & v_1 \\ & \times \\ u_2 & \underline{v_2} \end{array}$$

Proof.

$$\text{Vol}_2\left(\begin{pmatrix} u_1 \\ u_2 \end{pmatrix}, \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}\right) = \text{Vol}_2\left(\begin{pmatrix} u_1 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ u_2 \end{pmatrix}, \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}\right)$$

6

$$\stackrel{(1)}{=} \text{Vol}_2 \left(\begin{pmatrix} u_1 \\ 0 \end{pmatrix}, \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \right) + \text{Vol}_2 \left(\begin{pmatrix} 0 \\ u_2 \end{pmatrix}, \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \right)$$

4 Determinants

$$\stackrel{(1)}{=} \text{Vol}_2 \left(\begin{pmatrix} u_1 \\ 0 \end{pmatrix}, \begin{pmatrix} v_1 \\ 0 \end{pmatrix} \right) + \text{Vol}_2 \left(\begin{pmatrix} u_1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ v_2 \end{pmatrix} \right) \\ + \text{Vol}_2 \left(\begin{pmatrix} 0 \\ u_2 \end{pmatrix}, \begin{pmatrix} v_1 \\ 0 \end{pmatrix} \right) + \text{Vol}_2 \left(\begin{pmatrix} 0 \\ u_2 \end{pmatrix}, \begin{pmatrix} 0 \\ v_2 \end{pmatrix} \right) = 0 \quad (\text{Prop. 4.5})$$

$$\stackrel{(2)}{=} u_1 v_2 \underbrace{\text{Vol}_2 \left(\begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right)}_{=1 \text{ by (4)}} + u_2 v_1 \underbrace{\text{Vol}_2 \left(\begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right)}_{=-1 \text{ by (3), (4)}}$$

$$= u_1 v_2 - u_2 v_1 = \text{Area} \left(\begin{pmatrix} u_1 \\ u_2 \end{pmatrix}, \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \right) \checkmark$$

~> Do the same in n dimensions!

□

Note that this proves that the volume function Vol_2 is uniquely defined by the four properties (1), (2), (3) and (4) alone. We expect the same for arbitrary dimension n and indeed we prove this now.

For $\mathbf{a}_1 = \begin{pmatrix} a_{11} \\ \vdots \\ a_{n1} \end{pmatrix}, \dots, \mathbf{a}_n = \begin{pmatrix} a_{1n} \\ \vdots \\ a_{nn} \end{pmatrix} \in \mathbb{R}^n$, it follows

$$\text{Vol}_n(\mathbf{a}_1, \dots, \mathbf{a}_n) = \text{Vol}_n(a_{11}\mathbf{e}_1 + \dots + a_{n1}\mathbf{e}_n, \dots, a_{1n}\mathbf{e}_1 + \dots + a_{nn}\mathbf{e}_n). \quad (*)$$

Using the linearity in each entry, we can conclude:

$$\text{Vol}_n(\mathbf{a}_1, \dots, \mathbf{a}_n) \stackrel{(1)}{=} \text{Vol}_n(a_{11}\mathbf{e}_1, (*)) + \text{Vol}_n(a_{21}\mathbf{e}_2 + \dots + a_{n1}\mathbf{e}_1, (*)) \\ \stackrel{(2)}{=} a_{11} \text{Vol}_n(\mathbf{e}_1, (*)) + a_{21} \text{Vol}_n(\mathbf{e}_2, (*)) + \dots \text{ the same for the other ones}$$

$$= \sum_{i_1=1}^n a_{i_1 1} \text{Vol}_n(e_{i_1}, \underbrace{a_{12}e_1 + \dots + a_{n2}e_n, \dots, a_{1n}e_1 + \dots + a_{nn}e_n}_{\text{Do it again!}})$$

$$\text{Vol}_n(\mathbf{a}_1, \dots, \mathbf{a}_n) = \sum_{i_1=1}^n \sum_{i_2=1}^n \dots \sum_{i_n=1}^n a_{i_1,1} a_{i_2,2} \dots a_{i_n,n} \text{Vol}_n(e_{i_1}, e_{i_2}, \dots, e_{i_n})$$

= 0 if two indices coincide (by (3))

= ±1 depending on the permutation

$$= \sum_{(i_1, \dots, i_n) \in \{1, \dots, n\} \times \dots \times \{1, \dots, n\}}$$

↑ actually, we only need to sum over (i_1, \dots, i_n) where each one is different: List of the numbers $1, \dots, n$ (in any order)

→ permutation of the set $\{1, \dots, n\} \rightarrow \mathcal{P}_n = \text{All permutations}$

Example: $(1, 2, 4, 3, 5) \in \mathcal{P}_5$ is an ^{odd} permutation of $\{1, \dots, n\}$

[Alternatively: permutation: map: $\tau: \{1, \dots, n\} \rightarrow \{1, \dots, n\}$ bijective]

For a permutation $\tau \in \mathcal{P}_n$, we define $\text{sgn}(\tau) = 1$ if one can use an even number of exchanges of two elements to get from τ to $(1, 2, \dots, n)$. If one needs an odd number of exchanges of two elements to get from τ to $(1, 2, \dots, n)$, we define $\text{sgn}(\tau) = -1$.

Repeatable usage of (3) shows $\text{Vol}_n(e_{i_1} \dots e_{i_n}) = \text{sgn}(i_1, \dots, i_n)$. In summary, we get

Proposition 4.7. Leibniz formula

The volume form Vol_n is uniquely determined by the properties (1),(2),(3) and (4)

and fulfils for n vectors $\mathbf{a}_1 = \begin{pmatrix} a_{11} \\ \vdots \\ a_{n1} \end{pmatrix}, \dots, \mathbf{a}_n = \begin{pmatrix} a_{1n} \\ \vdots \\ a_{nn} \end{pmatrix} \in \mathbb{R}^n$:

$$\text{Vol}_n(\mathbf{a}_1, \dots, \mathbf{a}_n) = \sum_{(i_1, \dots, i_n) \in \mathcal{P}_n} \text{sgn}(i_1, \dots, i_n) a_{i_1,1} a_{i_2,2} \dots a_{i_n,n} \quad (4.2)$$

Proof. The calculation from above shows that (4.2) is the only function that fulfils all the four rules. □

In \mathbb{R}^2 : Only two permutations in \mathcal{P}_2 : $\begin{matrix} i_1 & i_2 \\ (1, 2), & (2, 1) \end{matrix}$

$$\text{Vol}_2(\mathbf{a}_1, \mathbf{a}_2) = a_{11} a_{22} - a_{21} a_{12}$$

Definition 4.8. Determinant of square matrices

For a square matrix $A \in \mathbb{R}^{n \times n}$ with entries

$$A := \begin{pmatrix} | & & | \\ \mathbf{a}_1 & \cdots & \mathbf{a}_n \\ | & & | \end{pmatrix} = \begin{pmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & & \vdots \\ a_{n1} & \cdots & a_{nn} \end{pmatrix},$$

we define the determinant as the volume measure of the column vectors:

$$\det(A) := \text{Vol}_n(\mathbf{a}_1, \dots, \mathbf{a}_n) = \sum_{(i_1, \dots, i_n) \in \mathcal{P}_n} \text{sgn}(i_1, \dots, i_n) a_{i_1, 1} a_{i_2, 2} \cdots a_{i_n, n}.$$

Remark:

You can remember the Leibniz formula of the determinant $\det(A)$ in the following way:

- (1) Build a product of n factors out of the entries in A . From each row and each column you are only allowed to choose one factor.
- (2) Sum up all the possibilities for such a product where you add a minus-sign for the odd permutations.

Example 4.9. Consider the matrix $P_{k \leftrightarrow \ell}$ that we used in the Gaussian elimination to switch the k th row with the ℓ th row. Let's denote the entries by p_{ij} and then we know

Example:

$$P = \begin{pmatrix} 1 & & & & & \\ & \ddots & & & & \\ & & 1 & & & \\ & & & \ddots & & \\ & & & & 1 & \\ & & & & & \ddots \\ & & & & & & 1 \end{pmatrix}$$

$$p_{ij} = \begin{cases} 1 & \text{if } i = j \text{ and } i, j \neq k, \ell \\ 1 & \text{if } i = k, j = \ell \text{ or } i = \ell, j = k \\ 0 & \text{else} \end{cases}$$

$$\det(P_{k \leftrightarrow \ell}) = \sum_{\tau \in \mathcal{P}_n} \text{sgn}(\tau) p_{11} \cdots p_{k,\ell} \cdots p_{\ell,k} \cdots p_{nn} = -1$$

\uparrow odd

Since the permutation is only one single exchange, the sign is -1 . Of course, we expect this result by property (3) of the volume form.

Recall: Leibniz formula \leadsto sum up $n!$ terms
 $\leadsto n=2 \quad 2! = 2$

n

$\rightarrow n = 3$

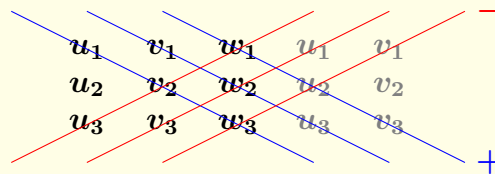
$3! = 6$

$\rightarrow n = 4$

$4! = 24$

$$\det \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} = + a_{11}a_{22}a_{33} + a_{12}a_{23}a_{31} + a_{13}a_{21}a_{32} - a_{13}a_{22}a_{31} - a_{11}a_{23}a_{32} - a_{12}a_{21}a_{33}$$

Rule of thumb: Rule of Sarrus (Only for $n = 3$)



$$\text{Vol}(\mathbf{u}, \mathbf{v}, \mathbf{w}) = +u_1v_2w_3 + v_1w_2u_3 + w_1u_2v_3 - u_3v_2w_1 - v_3w_2u_1 - w_3u_2v_1$$

Moreover, the sign of the three-dimensional volume can be easily seen by the right-hand-rule:

