$\left(\begin{array}{ccc} 1 & 2 & 3 \\ \hline 4 & 5 & 6 \end{array}\right) + \left(\begin{array}{ccc} 7 & 8 \\ g & 10 \end{array}\right) \quad is \quad \underline{net} \quad defind$

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Attention!

The addition A + B is only defined for matrices with the same height and the same width.

Definition 3.4. Scalar \cdot Matrix = Matrix

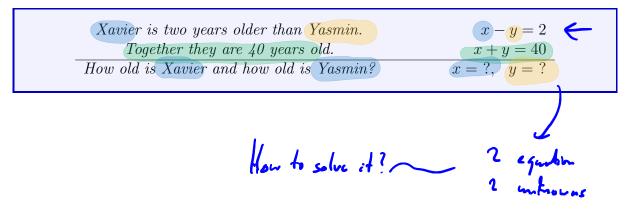
Let $A \in \mathbb{R}^{m \times n}$ and $\lambda \in \mathbb{R}$. Then the scalar multiplication $\lambda \cdot A \in \mathbb{R}^{m \times n}$ is defined by: $\lambda \cdot \begin{pmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \vdots \\ a_{m1} & \cdots & a_{mn} \end{pmatrix} := \underbrace{\begin{pmatrix} \lambda a_{11} & \cdots & \lambda a_{1n} \\ \vdots & \vdots \\ \lambda a_{m1} & \cdots & \lambda a_{mn} \end{pmatrix}}_{\lambda \cdot A}.$

Example 3.5.

$$2\begin{pmatrix}1&2\\3&4\end{pmatrix} = \begin{pmatrix}2\cdot1&2\cdot2\\2\cdot3&2\cdot4\end{pmatrix} = \begin{pmatrix}2&4\\6&8\end{pmatrix} = \begin{pmatrix}1&2\\3&4\end{pmatrix} + \begin{pmatrix}1&2\\3&4\end{pmatrix}. \quad \textbf{e} \quad \textbf{A} \neq \textbf{A}$$

3.1 Introduction to systems of linear equations

We start with some easy examples:



This was an example with two unknowns (x and y). Here we give an example for three unknowns. (x, y and z):

$$2x -3y +4z = -7$$

$$-3x +y -z = 0$$

$$20x +10y = 80$$

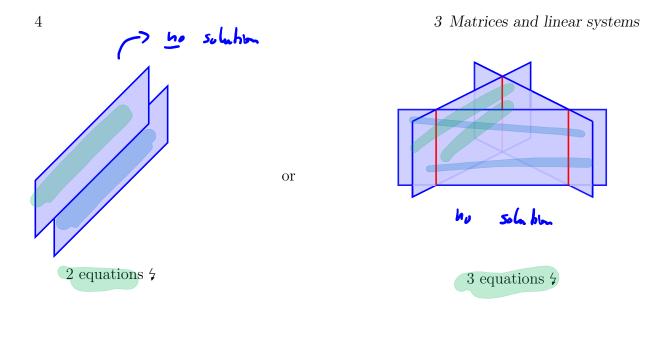
$$10y +25z = 90$$

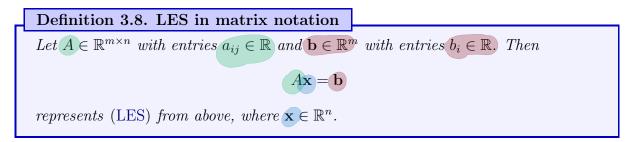
$$4 e quebers$$

$$3 wr known s$$

3.1 Introduction to systems of linear equations

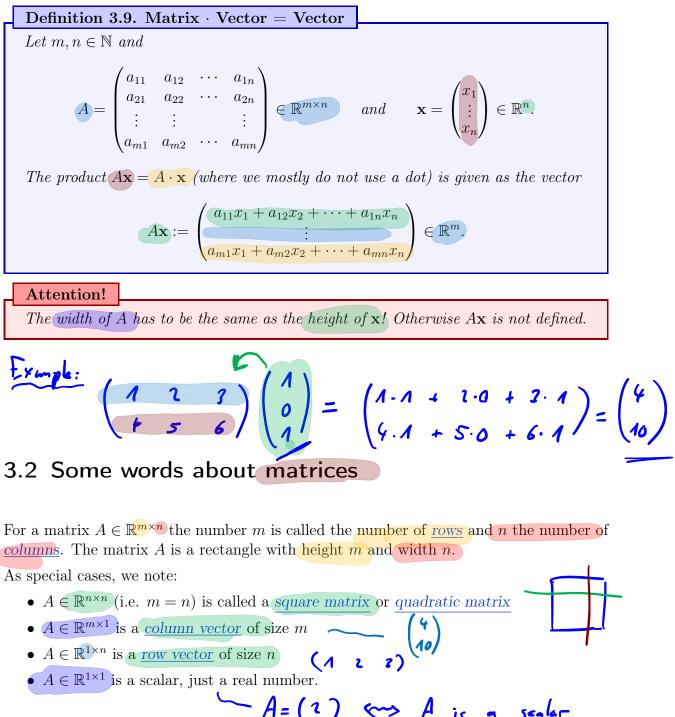
, he IN , he N Unknowns: (XA, ..., Xh) Number of equations: h Which when for XA, ..., Xh Schisfy all equations at ance. Question: Solution Here, the most important part is that the equations are linear. The exact definition will follow later. The sloppy way to say that an equation is linear is: constant $\cdot x_1$ + constant $\cdot x_2$ + \cdots + constant $\cdot x_n$ = constant. (3.1)7 just As you can see, there are a lot of constants that have to be numeric. Definition 3.6. System of linear equations (LES) Let $m, n \in \mathbb{N}$ be two natural numbers. A system of linear equations or a linear equation system (abbreviation: <u>LES</u>) with m equations and n unknowns x_1, x_2, \dots, x_n is given by: $a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$ $a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$ (LES) $a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m$ Here, a_{ij} and b_i are given numbers, mostly just real numbers. A solution of the LES is a choice of values for $x_1, ..., x_n$ such that all m equations are satisfied. 1st question: Existence 2. 2nd question: Unigracer? **Example 3.7.** Having three unknowns x_1, x_2, x_3 , we could have different cases for the set \bigwedge of solutions: Vector 1R3 ~> Equilions describe affine subspaces (e.g. translated plane solution set E_2 existic V miguness f E_1





The two examples from above in this notation:

$$\begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 2 \\ 40 \end{pmatrix}, \quad \begin{pmatrix} 2 & -3 & 4 \\ -3 & 1 & -1 \\ 20 & 10 & 0 \\ 0 & 10 & 25 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -7 \\ 0 \\ 80 \\ 90 \end{pmatrix}.$$
Matrix Vecher Vecher Vecher Matrix - Vecher und Eplicchion !

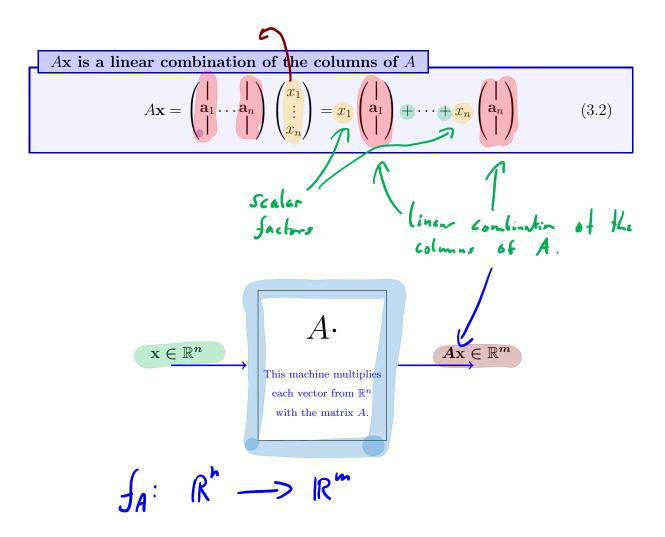


$$A = \begin{pmatrix} a_{nn} & a_{nn} & a_{ns} \\ a_{2n} & a_{2n} & a_{2s} \\ a_{3n} & a_{2n} & a_{2s} \\ a_{3n} & a_{3n} & a_{3n} \\ a_{3n} & a_{3$$

3.3 Looking at the columns and the associated linear map

One way to imagine a matrix in $\mathbb{R}^{m \times n}$ is to see it as a collection of n columns of size m:

$$A = \begin{pmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{m1} & \dots & a_{mn} \end{pmatrix} = \begin{pmatrix} | & | \\ \mathbf{a}_1 & \dots & \mathbf{a}_n \end{pmatrix}, \text{ where } \mathbf{a}_i = \begin{pmatrix} a_{1i} \\ \vdots \\ a_{mi} \end{pmatrix} \in \mathbb{R}^m$$



The function f_A defined by the matrix A			<u> </u>	
	$f_A: \mathbb{R}^n \to \mathbb{R}^m,$	with	$f_A: \mathbf{x} \mapsto A\mathbf{x}$	(3.3)
~~>	see luter :	fa	finear map	

3.4 Looking at the rows

Above, we have considered a matrix $A \in \mathbb{R}^{m \times n}$ as a collection of columns and defined a linear map $f_A : \mathbb{R}^n \to \mathbb{R}^m$. However, we may also see A as a collection of m rows of size n:

$$A = \begin{pmatrix} a_{11} & \dots & a_{1n} \\ \vdots & \vdots \\ a_{m1} & \dots & a_{mn} \end{pmatrix} = \begin{pmatrix} -\boldsymbol{\alpha}_1^T - \\ \cdots \\ -\boldsymbol{\alpha}_m^T - \end{pmatrix}, \text{ where } \boldsymbol{\alpha}_i^T = \begin{pmatrix} a_{i1} & \cdots & a_{in} \end{pmatrix}$$

Here, we use the notation T for the *transpose* of a column vector. The result is a row vector with the same entries. We fix this as a space:) (K_A ... X_m)

$$\mathbb{R}^{1 \times n} = \{ \mathbf{x}^T = (x_1 \dots x_n) : x_1, \dots, x_n \in \mathbb{R} \}$$

Since a row vector $\mathbf{u}^T \in \mathbb{R}^{1 \times n}$ is just a very flat matrix, the product with a column vector $\mathbf{v} \in \mathbb{R}^n$ is well-defined: LVE IR"

$$\mathbf{u}^{T}\mathbf{v} = (u_{1}v_{1} + \dots + u_{n}v_{n}) \in \mathbb{R}^{1 \times 1}.$$

$$\mathbf{u}^{T} \in \mathbb{R}^{4 \times n}$$

$$\begin{pmatrix} 1 & 2 & 2 \end{pmatrix} \begin{pmatrix} 2 & 4 \\ 4 & 4 \end{pmatrix} = (2 + 8 + 48) = (2 + 8 + 18) = (2 + 8 + 18) = 28$$

$$\mathbf{v} \geq \mathbf{u}^{T}\mathbf{v}$$

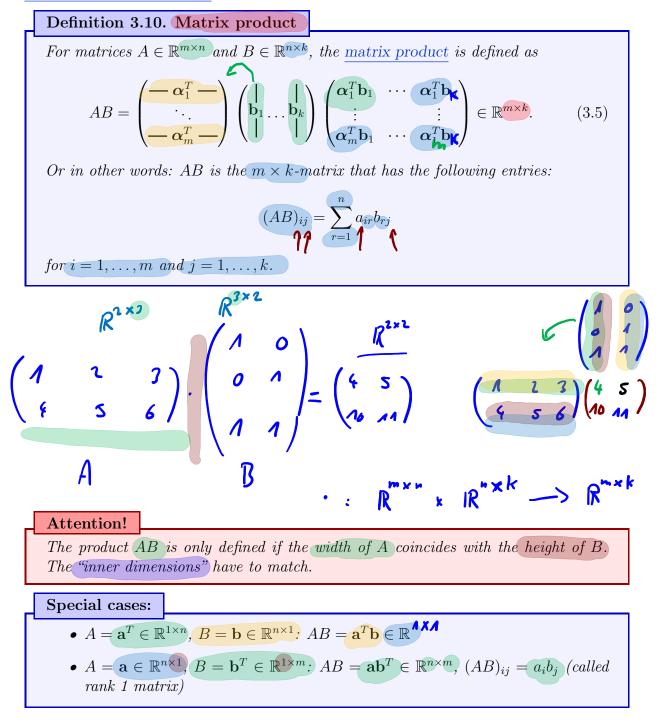
Ax is the scalar product of x with the rows of A

$$Ax = \begin{pmatrix} -\alpha_1^T - \\ \ddots \\ -\alpha_m^T - \end{pmatrix} \begin{pmatrix} | \\ x \\ | \\ | \end{pmatrix} = \begin{pmatrix} \alpha_1^T x \\ \vdots \\ \alpha_n^T x \end{pmatrix} \qquad (3.4)$$

3.5 Matrix multiplication
$$A \cdot B$$

Let $A \in \mathbb{R}^{m \times n}$. $b \in i\mathbb{R}^{n} \longrightarrow Ab \in \mathbb{R}^{n}$
 $b_{1}, \dots, b_{k} \in i\mathbb{R}^{n} \longrightarrow Ab_{k}, \dots, Al_{k} \in \mathbb{R}^{m}$
 $B = (b_{1} \dots b_{k}) \in i\mathbb{R}^{n \times k} \longrightarrow (Ab_{k} \dots Ab_{k}) \in \mathbb{R}^{m \times k}$
 $A (b_{1} \dots b_{k}) = (Ab_{1} Ab_{2} \dots Ab_{k})$ for k column vectors b_{1}, \dots, b_{k}

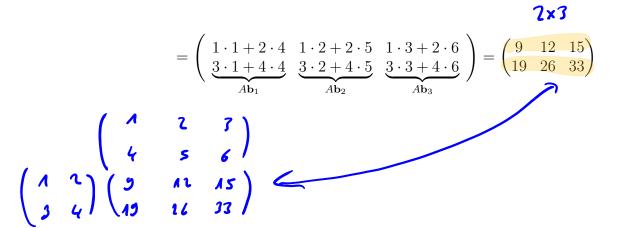
The result is a matrix with m rows and k columns and denoted by AB. It is called the matrix product of A and B.



Example 3.11. Just calculate some examples:

(a) We combine the following matrix dimensions $(2 \times 2) \cdot (2 \times 3) \Rightarrow 2 \times 3$:

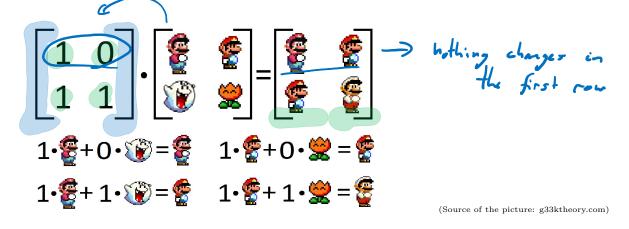
$$\underbrace{\begin{pmatrix}1&2\\3&4\end{pmatrix}}_{A}\underbrace{\begin{pmatrix}1&2&3\\4&5&6\end{pmatrix}}_{B} = \left(\underbrace{\begin{pmatrix}1&2\\3&4\end{pmatrix}}_{A}\underbrace{\begin{pmatrix}1\\4\end{pmatrix}}_{\mathbf{b}_{1}} \quad \underbrace{\begin{pmatrix}1&2\\3&4\end{pmatrix}}_{A}\underbrace{\begin{pmatrix}2\\5\end{pmatrix}}_{\mathbf{b}_{2}} \quad \underbrace{\begin{pmatrix}1&2\\3&4\end{pmatrix}}_{A}\underbrace{\begin{pmatrix}3\\6\end{pmatrix}}_{\mathbf{b}_{3}}\right)$$



(b) Let
$$A = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix}$$
 and $B = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$. **But**: **B**•A is defined
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(d) Now the matrix dimensions $(1 \times 3) \cdot (3 \times 1) \Rightarrow 1 \times 1$: $(1 \ 2 \ 3) \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} = (1 \cdot 1 + 2 \cdot 2 + 3 \cdot 3) = (14) = 14$ *1 1*

(e) A 2×2 -example:



We can also ask what happens if we multiply a row vector \mathbf{x}^T from the left to a matrix B. By definition, we get:

$$\mathbf{x}^{T}B = (x_{1} \cdots x_{n}) \begin{pmatrix} -\boldsymbol{\beta}_{1}^{T} \\ \vdots \\ -\boldsymbol{\beta}_{n}^{T} \end{pmatrix} = x_{1} (-\boldsymbol{\beta}_{1}^{T} -) + \cdots + x_{n} (-\boldsymbol{\beta}_{n}^{T} -) .$$

This means the product $\mathbf{x}^T B$ is a linear combination of the rows of B. This is an analogy that $A\mathbf{x}$ is a linear combination of the columns of A, cf. equation (3.4).

Remark:

Now we can see the matrix product as introduced

$$AB = \begin{pmatrix} A\mathbf{b}_1 & A\mathbf{b}_2 & \dots & A\mathbf{b}_k \\ \mathbf{b}_1 & \mathbf{b}_2 & \dots & \mathbf{b}_k \end{pmatrix}$$

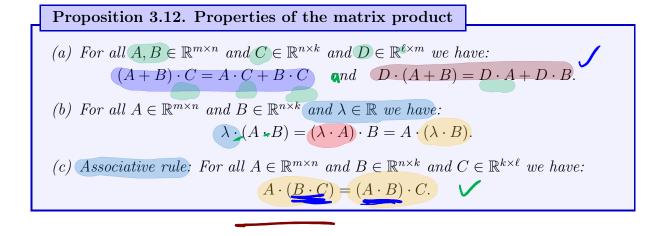
This means that each column of AB consists of a linear combination of the columns from A.

Seeing the product with the other eye

$$AB = \begin{pmatrix} -\alpha_1^T \\ \vdots \\ -\alpha_m^T \end{pmatrix} B = \begin{pmatrix} -\alpha_1^T B \\ \vdots \\ -\alpha_m^T B \end{pmatrix}$$

we see that each row of AB consists of a linear combination of the rows from B.

Now, we summarise the properties of the matrix multiplication.



Proof. All these rules follow from the definition of the matrix product of A and B,



and the fact that these rules hold for the real numbers $a_{ir}, b_{rj} \in \mathbb{R}$. For example, for showing (c):

$$(A(BC))_{ij} = \sum_{r=1}^{n} a_{ir}(BC)_{rj} = \sum_{r=1}^{n} a_{ir} \sum_{z=1}^{n} b_{rz}c_{zj} = \sum_{z=1}^{n} \left(\sum_{r=1}^{n} a_{ir}b_{rz}\right)c_{zj} = ((AB)C)_{ij}.$$
Properties (a) and (b) are left as an exercise.
$$(a_{rin})_{rin} e_{rin} e_{rin}$$

Remark:

We thus have the following interpretations of the matrix vector product AB:

- the columns of B are used to build linear combinations of the columns of A,
- the rows of A are used to build linear combinations of the rows of B,
- each row $\boldsymbol{\alpha}_i^T$ of A and each column \mathbf{b}_j of B are multiplied to form an entry of the product: $(AB)_{ij} = \boldsymbol{\alpha}_i^T \mathbf{b}_j$,
- each column \mathbf{a}_i of A and each row $\boldsymbol{\beta}_i^T$ of B is combined to a rank-1 matrix $\mathbf{a}_i \boldsymbol{\beta}_i^T$, and the matrices are added up,

All these interpretations are equally valid, and from situation to situation, we can change our point of view to gain additional insights.